

WOF

v1.12

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## 1 Main Page

### WOF C++ Point Cloud Mesher

- **Point cloud to mesh** - Fast surface reconstruction software
- **Mesh to point cloud** - Quality point cloud creator
- **Mesh to mesh** - Convert a mesh into a point cloud and reconstruct it from there

WOF is as a **C++ library and command line executable** for Windows and Linux development.

#### Download the WOF library and command line application

There are two WOF builds:

- **WOF PURE** comes without any dependencies so it can be integrated smoothly. It includes a 500 000 points student/eval license.
- **WOF LM** comes with a license manager (LM) and allows an unlimited number of points during the trial period.

Both variants contain a dynamic C++ library, a command line application, C++ examples and documentation.

## License

WOF is a commercial project with maintenance and support.

- A free **student license** for non-commercial research and evaluation is included in the PURE build. It allows 500 000 points.
  - The LM build includes an **evaluation license** for research and commercial tests. It is unlimited during the trial period. If you want to use WOF in your commercial project, please contact the author and give as much information as possible.
- 

## Release Notes and Version History

### Version 1.12, Sep 29th, 2022:

- New hole closing algorithm, use the -H option
- Stability improved

### Version 1.11, May 23rd, 2022:

- Bugfix when no work in progress bar
- New function `estimateAvgSpacing()` to estimate the density of a point cloud

### Version 1.10, May 7th, 2022:

- Progress bar support
- Two separate variants: PURE and LM
- Extended API for detailed control over mesh reduction, mesh smoothing and edge flips.
- C++ example improved

### Version 1.09, March 16th, 2022:

- Laplacian smoothing removes noise
- Edge flips fit the triangulation to the thought surface
- Mesh simplification reduces the number of triangles
- Better performance
- Multithreading improved
- Bugfixes
- Enhanced C++-API

### Version 1.08, February 17th, 2022:

- Another bugfix

### Version 1.07, February 16th, 2022:

- Bugfix in yesterday's version

**Version 1.06, February 15th, 2022:**

- Mesh melting improved.
- Tiny holes due to poor sampling are better avoided.
- Bugs solved.
- Quality improved.

**Version 1.05, July 6th, 2021:**

- Improved mesh melting

**Version 1.04, April 3rd, 2020:**

- Static and dynamic linking is now available (*static linking since v1.10 to reduce the complexity*)
- CMake improved, Visual Studio project, Makefile
- Example data exchanged

**Version 1.03, March 23rd, 2020:**

First official release of the WOF software:

- Readers and Writers for the \*.ply, \*.stl, \*.asc, \*.bin, \*.list file formats exist now
- A Mesh-to-Cloud method has been added
- An API has been made
- The library has been tested for memory leaks
- Documentation pages have been written

**Version Beta2, October 2019**

- Reconstruction quality improved
- Library versions added

**Version Beta1, March 2019**

- This software is developed since 2016 when it was a module of the Fade2D software.
- For flexibility reasons the whole point cloud topic has been moved to the separate WOF project now.

## 2 Module Index

### 2.1 Modules

Here is a list of all modules:

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## 3 Namespace Index

### 3.1 Namespace List

Here is a list of all documented namespaces with brief descriptions:

|                          |    |
|--------------------------|----|
| <a href="#">GEOM_WOF</a> | 15 |
|--------------------------|----|

## 4 Hierarchical Index

### 4.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:  
std::exception

|                               |    |
|-------------------------------|----|
| GEOM_WOF::WofBugException     | 30 |
| GEOM_WOF::WofLicenseException | 30 |
| GEOM_WOF::Mesh                | 18 |
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| GEOM_WOF::TimerC              | 25 |
| GEOM_WOF::Vector3             | 26 |

## 5 Class Index

### 5.1 Class List

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| <a href="#">GEOM_WOF::Point3</a><br>3D Point                                  | 20 |
| <a href="#">GEOM_WOF::ProgressBase</a><br>Base class for progress subscribers | 25 |
| <a href="#">GEOM_WOF::TimerC</a><br>Timer class                               | 25 |
| <a href="#">GEOM_WOF::Vector3</a><br>3D Vector                                | 26 |
| <a href="#">GEOM_WOF::WofBugException</a><br>Bug-Exception                    | 30 |
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## 6 File Index

### 6.1 File List

Here is a list of all documented files with brief descriptions:

|                                       |                    |
|---------------------------------------|--------------------|
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| <b>Point3.h</b>                       | ??                 |
| <b>TimerC.h</b>                       | ??                 |
| <b>Vector3.h</b>                      | ??                 |
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| <a href="#">wof_api_io.h</a>          | <a href="#">33</a> |

## 7 Module Documentation

### 7.1 License related functions

License related functions for "LM" builds.

#### Macros

- #define [WOFLIC\\_ACTIVATED](#) 10
- #define [WOFLIC\\_GRACE\\_OK](#) 11
- #define [WOFLIC\\_GRACE\\_EXPIRED](#) 12
- #define [WOFLIC\\_TRIAL](#) 13
- #define [WOFLIC\\_INVALID](#) 14
- #define [WOFLIC\\_PURE](#) 15

#### Functions

- int [GEOM\\_WOF::getLicenseState](#) ()  
*Check the license state.*
- void [GEOM\\_WOF::printLicense](#) ()  
*Print license details.*
- bool [GEOM\\_WOF::isPure](#) ()  
*Check if pure or lm build.*
- bool [GEOM\\_WOF::activateWof](#) (const char \*key, bool bSystemWide)  
*Activate WOF license.*
- bool [GEOM\\_WOF::deactivateWof](#) ()  
*Deactivate WOF license.*
- bool [GEOM\\_WOF::extendTrial](#) (const char \*key)  
*Extend Trial.*

#### 7.1.1 Detailed Description

Functions related to the license: Activation, deactivation, trial-extension... Not active in "PURE" builds.

#### 7.1.2 Macro Definition Documentation

#### 7.1.2.1 WOFLIC\_ACTIVATED `#define WOFLIC_ACTIVATED 10`

WOFLIC\_ACTIVATED means the software is activated

#### 7.1.2.2 WOFLIC\_GRACE\_EXPIRED `#define WOFLIC_GRACE_EXPIRED 12`

WOFLIC\_GRACE\_EXPIRED means the software is activated but re-verification (no internet) has failed for a long time. Invalid.

#### 7.1.2.3 WOFLIC\_GRACE\_OK `#define WOFLIC_GRACE_OK 11`

WOFLIC\_GRACE\_OK means the software is activated but re-verification has failed (no internet, valid for a sufficiently long grace period)

#### 7.1.2.4 WOFLIC\_INVALID `#define WOFLIC_INVALID 14`

WOFLIC\_INVALID means there is no valid license (trial, product-key)

#### 7.1.2.5 WOFLIC\_PURE `#define WOFLIC_PURE 15`

WOFLIC\_PURE is the perpetual non-commercial license

#### 7.1.2.6 WOFLIC\_TRIAL `#define WOFLIC_TRIAL 13`

WOFLIC\_TRIAL means the trial period is still active

### 7.1.3 Function Documentation

**7.1.3.1 activateWof()** `bool GEOM_WOF::activateWof (`  
    `const char * key,`  
    `bool bSystemWide )`

This function is used when you have a WOF license key. You can choose to activate system-wide or only for the current user.

#### Parameters

|                    |   |
|--------------------|---|
| <i>key</i>         | is the purchased software key   |
| <i>bSystemWide</i> | When true then the activation data is stored system-wide. When false the activation is made for the current user. |

#### Note

Activation is only done once. You can use [getLicenseState\(\)](#) to find out if the software is already activated.

When the system-wide activation is chosen (`bSystemWide=true`) then the application needs admin-privileges.

**7.1.3.2 deactivateWof()** `bool GEOM_WOF::deactivateWof ( )`

Deactivates the WOF license on the present computer so that the key can be used on another machine. This function enables you to replace a computer. Do not use over-frequently, the number of deactivations is limited, it's not a floating license.

#### Returns

true in case of success, false otherwise

**7.1.3.3 extendTrial()** `bool GEOM_WOF::extendTrial (`  
    `const char * key )`



## Parameters

|            |  |
|------------|--|
| <i>key</i> | is a Trial-Extension-key. You ask for such a key to extend the trial period for your non-commercial research project (see the guidelines) or for an extended commercial test period. |
|------------|--|

## Returns

true in case of success, false otherwise

7.1.3.4 `getLicenseState()` `int GEOM_WOF::getLicenseState ( )`

## Returns

`WOFLIC_ACTIVATED` when the software is activated

`WOFLIC_TRIAL` during the trial period

`WOFLIC_GRACE_OK` when activated but verification has failed (no internet access) which is valid for a grace period

`WOFLIC_GRACE_EXPIRED` when activated but verification has failed (no internet) for a long time

`WOFLIC_INVALID` otherwise (trial expired, no license)

## 7.2 Version related functions

Version related functions.

## Functions

- void `GEOM_WOF::printVersion ( )`  
*Print version number.*
- void `GEOM_WOF::getVersion (int &versionMajor, int &versionMinor)`  
*Get version numbers.*
- bool `GEOM_WOF::isRelease ( )`  
*Check if the present binary is a Release or Debug build.*

## 7.2.1 Detailed Description

Functions to identify Debug- and Release builds and to fetch the version number.

## 7.2.2 Function Documentation

7.2.2.1 `getVersion()` `void GEOM_WOF::getVersion (int &versionMajor, int &versionMinor )`

Returns the WOF version number

## Parameters

|                                  |   |
|----------------------------------|---|
| <i>versionMajor,versionMinor</i> | [out] are used to return the major and minor version number |
|----------------------------------|---|

7.2.2.2 `isRelease()` `bool GEOM_WOF::isRelease ( )`

## Returns

true when the library has been compiled in release mode or false otherwise

### 7.2.2.3 printVersion() `void GEOM_WOF::printVersion ( )`

Prints the version number to stdout

## 7.3 Geometry functions

Geometry operations.

### Functions

- `MeshPtr GEOM_WOF::melt` (`std::vector< Point3 > &vInputCorners`, `double avgLength`, `double featureThresh=15.0`)  
*Remesh (melt) a triangle mesh.*
- `MeshPtr GEOM_WOF::reconstruct_auto` (`std::vector< Point3 > &vPoints`, `bool bAllowSmoothing`, `double sfactor=2.0`, `int numGrowSteps=10`)  
*Reconstruct with an automatic spacing value.*
- `MeshPtr GEOM_WOF::reconstruct_abs` (`std::vector< Point3 > &vPoints`, `bool bAllowSmoothing`, `double spacingAbs`, `int numGrowSteps=10`)  
*Reconstruct with an absolute spacing value.*
- `void GEOM_WOF::toCloud` (`std::vector< Point3 > &vCornersIn`, `double length`, `double featureThresh`, `std::vector< Point3 > &vCloudOut`)  
*Mesh-to-Cloud.*
- `void GEOM_WOF::edgeFlips` (`MeshPtr pMesh`)  
*Flip edges.*
- `void GEOM_WOF::edgeFlipsSimA` (`MeshPtr pMesh`)  
*Flip edges - simulated annealing.*
- `void GEOM_WOF::laplacianSmoothing` (`MeshPtr pMesh`, `int numIterations`)  
*Laplacian smoothing.*
- `int GEOM_WOF::reduce` (`MeshPtr pMesh`, `double targetLen=DBL_MAX`, `double maxDev=2.0`)  
*Reduce.*

### 7.3.1 Detailed Description

Operations to reconstruct a surface, to sample-and-reconstruct a mesh and to create feature-aligned quality point clouds.

### 7.3.2 Function Documentation

#### 7.3.2.1 edgeFlips() `void GEOM_WOF::edgeFlips ( MeshPtr pMesh )`

This function uses a simple and fast edge-flip algorithm to fit the mesh better to thought surface.

#### Parameters

|    |                    |                            |
|----|--------------------|----------------------------|
| in | <code>pMesh</code> | is the mesh to be improved |
|----|--------------------|----------------------------|

See also

[edgeFlipsSimA\(\)](#)

**7.3.2.2 edgeFlipsSimA()** `void GEOM_WOF::edgeFlipsSimA (   
 MeshPtr pMesh )`

Like [edgeFlips\(\)](#) the present function flips edges to adapt the mesh better to the thought surface. But with a computationally more expensive simulated annealing algorithm that achieves yet better output quality.

Parameters

|    |              |                            |
|----|--------------|----------------------------|
| in | <i>pMesh</i> | is the mesh to be improved |
|----|--------------|----------------------------|

See also

[edgeFlips\(\)](#)

**7.3.2.3 laplacianSmoothing()** `void GEOM_WOF::laplacianSmoothing (   
 MeshPtr pMesh,   
 int numIterations )`

This function applies weighted laplacian smoothing to create a smoother mesh.

Parameters

|    |                      |  |
|----|----------------------|--|
| in | <i>pMesh</i>         | is the mesh to be improved                     |
| in | <i>numIterations</i> | specifies how much the mesh shall be smoothed. |

**7.3.2.4 melt()** `MeshPtr GEOM_WOF::melt (   
 std::vector< Point3 > & vInputCorners,   
 double avgLength,   
 double featureThresh = 15.0 )`

This function converts a mesh into a point cloud and then reconstructs it from there. This way you can get rid of meshing errors and unnecessary complexity. This mesh-melting operation may change the topology of the object i.e., depending on the sample distance it may close holes and create additional bridges.

Parameters

|    |                      |  |
|----|----------------------|--|
| in | <i>vInputCorners</i> | contains the input triangles (3 corner points per triangle)  |
| in | <i>avgLength</i>     | specifies the average distance to be used. Choose this parameter with care to avoid an extreme number of elements.                     |
| in | <i>featureThresh</i> | is an optional parameter that specifies that edges above this value shall be treated as feature lines on which points shall be placed. |

**7.3.2.5 reconstruct\_abs()** `MeshPtr GEOM_WOF::reconstruct_abs (   
 std::vector< Point3 > & vPoints,   
 bool bAllowSmoothing,   
 double spacingAbs,   
 int numGrowSteps = 10 )`

This function reconstructs a triangular mesh from a 3D point cloud.

**Parameters**

|    |                        |   |
|----|------------------------|---|
| in | <i>vPoints</i>         | contains the input point cloud  |
| in | <i>spacingAbs</i>      | is an absolute spacing value. Large values  |
| in | <i>bAllowSmoothing</i> | specifies if the point cloud shall be smoothed before reconstruction.   |
| in | <i>numGrowSteps</i>    | is the number of steps by which the boundaries of holes can grow to close the holes. The steps correspond approximately to the used spacing distance. Larger values close larger holes and can take considerably more time. |

**Returns**

the reconstructed mesh.

If the absolute spacing value is unknown then better use [reconstruct\\_auto\(\)](#) which automatically estimates the point cloud density.

**See also**

[reduce\(\)](#), [laplacianSmoothing\(\)](#), [edgeFlips\(\)](#), [edgeFlipsSimA\(\)](#) which are powerful postprocessing fuctions.

**7.3.2.6 reconstruct\_auto()** `MeshPtr GEOM_WOF::reconstruct_auto (`  
`std::vector< Point3 > & vPoints,`  
`bool bAllowSmoothing,`  
`double sfactor = 2.0,`  
`int numGrowSteps = 10 )`

This function reconstructs a triangular mesh from a 3D point cloud.

**Parameters**

|    |                        |   |
|----|------------------------|---|
| in | <i>vPoints</i>         | contains the input point cloud  |
| in | <i>bAllowSmoothing</i> | specifies if the point cloud shall be smoothed before reconstruction.   |
| in | <i>sfactor</i>         | is a factor on the estimated point cloud density. The average spacing in the point cloud is automatically estimated and multiplied by sfactor. Use larger values to avoid holes upfront and to create coarser meshes. By default sfactor=2.0. |
| in | <i>numGrowSteps</i>    | is the number of steps by which the boundaries of holes can grow to close the holes. The steps correspond approximately to the used spacing distance. Use 0 to deactivate. Larger values close larger holes but also take more time.          |

**Returns**

the reconstructed mesh.

**See also**

[reduce\(\)](#), [laplacianSmoothing\(\)](#), [edgeFlips\(\)](#), [edgeFlipsSimA\(\)](#) which are powerful postprocessing fuctions.

**7.3.2.7 reduce()** `int GEOM_WOF::reduce (`  
`MeshPtr pMesh,`  
`double targetLen = DBL_MAX,`  
`double maxDev = 2.0 )`

This function reduces the number of triangles in pMesh.

## Parameters

|    |                  |  |
|----|------------------|--|
| in | <i>pMesh</i>     | is the mesh to be simplified   |
| in | <i>targetLen</i> | is a limit on the edge length (the algorithm will skip larger edges). Default: DBL_MAX |
| in | <i>maximum</i>   | angle deviation per simplification step. Default: 2.0                                  |

## Returns

the number of removed triangles

**7.3.2.8 toCloud()** `void GEOM_WOF::toCloud (`  
`std::vector< Point3 > & vCornersIn,`  
`double length,`  
`double featureThresh,`  
`std::vector< Point3 > & vCloudOut )`

This function creates a 3D point cloud from an input mesh.

## Parameters

|     |                      |  |
|-----|----------------------|--|
| in  | <i>vCornersIn</i>    | contains the input triangles (3 corners per triangle)  |
| in  | <i>length</i>        | specifies the approximate distance to be used  |
| in  | <i>featureThresh</i> | is an optional parameter. Edges with larger dihedral angles are treated as feature edges and points are preferably placed there. |
| out | <i>vCloudOut</i>     | is used to return the point cloud  |

## 7.4 File I/O

IO functions.

## Enumerations

- enum `GEOM_WOF::FileType` {  
`GEOM_WOF::FT_STL` , `GEOM_WOF::FT_PLY` , `GEOM_WOF::FT_XYZ` , `GEOM_WOF::FT_BIN` ,  
`GEOM_WOF::FT_LIST` , `GEOM_WOF::FT_UNKNOWN` }  
*Filetype.*

## Functions

- `FileType GEOM_WOF::getFileType` (const std::string &filename)  
*Get File Type.*
- bool `GEOM_WOF::writePoints_ASCII` (const char \*filename, const std::vector< `Point3` > &vPoints)  
*Write points to an ASCII file.*
- bool `GEOM_WOF::writePoints_BIN` (const char \*filename, std::vector< `Point3` > &vPoints)  
*Write points to a binary file.*
- bool `GEOM_WOF::readPly` (const char \*filename, bool bReadPoints, std::vector< `Point3` > &vPointsOut)  
*Write points to a \*.ply file.*
- bool `GEOM_WOF::writePointsPly` (const std::string &filename, std::vector< `GEOM_WOF::Point3` > &vPoints, bool bASCII)
- bool `GEOM_WOF::readPoints_ASCII` (const char \*filename, std::vector< `Point3` > &vPoints)  
*Read points from an ASCII file.*
- bool `GEOM_WOF::readPoints_BIN` (const char \*filename, std::vector< `Point3` > &vPointsOut)  
*Read points from a binary file.*

- bool `GEOM_WOF::readSTL_ASCII` (const char \*filename, std::vector< [Point3](#) > &vTriangleCorners)  
*Read a mesh from ASCII STL.*
- bool `GEOM_WOF::readPoints_auto` (std::string &inFilename, std::vector< [Point3](#) > &vPoints)  
*Read points from a file (automatic detection)*
- bool `GEOM_WOF::writePoints_auto` (std::string &outFilename, std::vector< [Point3](#) > &vPoints, bool bASCII)  
*Write points to a file.*
- bool `GEOM_WOF::writeMesh_auto` (const std::string &filename, std::shared\_ptr< [Mesh](#) > pMesh, bool bASCII)  
*Write mesh to a file.*

### 7.4.1 Detailed Description

Read/Write functions for point clouds and triangle meshes.

### 7.4.2 Enumeration Type Documentation

#### 7.4.2.1 FileType `enum GEOM_WOF::FileType`

Enumerator

|            |   |
|------------|---|
| FT_STL     | FileType STL based on the filename extension [.stl].            |
| FT_PLY     | FileType PLY based on the filename extension [.ply].            |
| FT_XYZ     | FileType XYZ based on the filename extensions [.xyz .txt .asc]. |
| FT_BIN     | FileType BIN based on the filename extension [.bin].            |
| FT_LIST    | FileType LIST based on the filename extension [.list].          |
| FT_UNKNOWN | FileType UNKNOWN for unknown extensions.                        |

### 7.4.3 Function Documentation

#### 7.4.3.1 `getFileType()` `FileType GEOM_WOF::getFileType (` `const std::string & filename )`

Returns

the file type ( [FT\\_STL](#), [FT\\_PLY](#), [FT\\_XYZ](#), [FT\\_BIN](#), [FT\\_LIST](#), [FT\\_UNKNOWN](#)) based on the filename extension.

#### 7.4.3.2 `readPly()` `bool GEOM_WOF::readPly (` `const char * filename,` `bool bReadPoints,` `std::vector< Point3 > & vPointsOut )`

Parameters

|                    |  |
|--------------------|--|
| <i>filename</i>    | [in] is the input filename   |
| <i>bReadPoints</i> | [in] Use true to get only the points of the *.ply file. Otherwise, when you are interested in the triangles then use false to get 3 subsequent corners per triangle. |
| <i>vPointsOut</i>  | [out] is used to return the points   |

**Returns**

true when the operation was successful or false otherwise

**7.4.3.3 readPoints\_ASCII()** `bool GEOM_WOF::readPoints_ASCII (`  
`const char * filename,`  
`std::vector< Point3 > & vPoints )`

Reads points from a simple ASCII file. Expected file format: Three coordinates (x y z) per line, whitespace separated.

**Parameters**

|                 |                                    |
|-----------------|------------------------------------|
| <i>filename</i> | [in] is the input filename         |
| <i>vPoints</i>  | [out] is used to return the points |

**Returns**

true [in] in case of success or false otherwise

**7.4.3.4 readPoints\_auto()** `bool GEOM_WOF::readPoints_auto (`  
`std::string & inFilename,`  
`std::vector< Point3 > & vPoints )`

This function reads points from a \*.ply-File (ASCII or binary), an \*.xyz-File (ASCII, 3 coordinates per line), or a \*.bin-File (simple binary format). The file type is automatically determined from the filename extension.

**Parameters**

|            |                   |                              |
|------------|-------------------|------------------------------|
| <i>in</i>  | <i>inFilename</i> | is the input filename        |
| <i>out</i> | <i>vPoints</i>    | is used to return the points |

**Returns**

true in case of success, false otherwise

**7.4.3.5 readPoints\_BIN()** `bool GEOM_WOF::readPoints_BIN (`  
`const char * filename,`  
`std::vector< Point3 > & vPointsOut )`

**Parameters**

|                   |                                    |
|-------------------|------------------------------------|
| <i>filename</i>   | [in] is a binary input file        |
| <i>vPointsOut</i> | [out] is used to return the points |

**Returns**

true in case of success or false otherwise

**See also**

[writePoints\\_BIN\(\)](#)

**7.4.3.6 readSTL\_ASCII()** `bool GEOM_WOF::readSTL_ASCII (`  
`const char * filename,`  
`std::vector< Point3 > & vTriangleCorners )`

#### Parameters

|                         |   |
|-------------------------|---|
| <i>filename</i>         | [in] is the input filename                        |
| <i>vTriangleCorners</i> | [out] is used to return three points per triangle |

#### Returns

true when the operation was successful or false otherwise

**7.4.3.7 writeMesh\_auto()** `bool GEOM_WOF::writeMesh_auto (`  
`const std::string & filename,`  
`std::shared_ptr< Mesh > pMesh,`  
`bool bASCII )`

This function writes a [Mesh](#) to file. Available formats are \*.ply (ASCII or binary), \*.stl (only ASCII) and Geomview-\*.list (ASCII). The file type is automatically determined from the filename extension.

#### Parameters

|    |                 |   |
|----|-----------------|---|
| in | <i>filename</i> | is the output filename  |
| in | <i>pMesh</i>    | is the mesh to be written   |
| in | <i>bASCII</i>   | specifies that ASCII mode shall be used when the file can be written in ASCII- or binary mode (as it is the case for *.ply) |

#### Returns

true in case of success or false otherwise

**7.4.3.8 writePoints\_ASCII()** `bool GEOM_WOF::writePoints_ASCII (`  
`const char * filename,`  
`const std::vector< Point3 > & vPoints )`

Writes points to an ASCII file, three coordinates (x y z) per line, whitespace separated.

#### Note

Data exchange through ASCII files is easy and convenient but floating point coordinates are not necessarily exact when represented as decimal numbers and ASCII files are big compared to other formats. Thus writing binary files using [writePoints\\_BIN\(\)](#) is recommended.

#### Parameters

|                 |  |
|-----------------|--|
| <i>filename</i> | [in] is the output filename            |
| <i>vPoints</i>  | [in] contains the points to be written |

#### Returns

true when the operation was successful or false otherwise.



**7.4.3.9 writePoints\_auto()** `bool GEOM_WOF::writePoints_auto (`  
`std::string & outFilename,`  
`std::vector< Point3 > & vPoints,`  
`bool bASCII )`

This function writes points to a \*.ply-File, \*.xyz-File (ASCII, 3 coordinates per line), or a \*.bin-File (simple binary format). The file type is automatically determined from the filename extension.

#### Parameters

|    |                    |   |
|----|--------------------|---|
| in | <i>outFilename</i> | is the output filename  |
| in | <i>vPoints</i>     | contains the points to be written   |
| in | <i>bASCII</i>      | specifies that ASCII mode shall be used when the file can be written in ASCII- or binary mode (as it is the case for *.ply) |

#### Returns

true in case of success or false otherwise

**7.4.3.10 writePoints\_BIN()** `bool GEOM_WOF::writePoints_BIN (`  
`const char * filename,`  
`std::vector< Point3 > & vPoints )`

Writes a binary file, the format is: (int,size\_t,double,...,double)

Thereby the first int is always 30, the size\_t value is vPoints.size() and the double precision values are x0,y0,z0,...,xn,yn,zn.

#### Parameters

|    |                 |                                   |
|----|-----------------|-----------------------------------|
| in | <i>filename</i> | is the output filename            |
| in | <i>vPoints</i>  | contains the points to be written |

#### Returns

true when the operation was successful or false otherwise

#### See also

[readPoints\\_BIN\(\)](#)

## 8 Namespace Documentation

### 8.1 GEOM\_WOF Namespace Reference

#### Classes

- class [Point3](#)  
*3D Point*
- class [TimerC](#)  
*Timer class.*
- class [Vector3](#)  
*3D Vector*
- class [WofLicenseException](#)  
*License-Exception.*
- struct [WofBugException](#)  
*Bug-Exception.*

- class [ProgressBase](#)  
*Base class for progress subscribers.*
- class [Mesh](#)  
*3D [Mesh](#) class*

## Typedefs

- typedef std::shared\_ptr< [Mesh](#) > [MeshPtr](#)

## Enumerations

- enum [FileType](#) {  
    [FT\\_STL](#) , [FT\\_PLY](#) , [FT\\_XYZ](#) , [FT\\_BIN](#) ,  
    [FT\\_LIST](#) , [FT\\_UNKNOWN](#) }  
*Filetype.*

## Functions

- std::ostream & **operator**<< (std::ostream &stream, const [Point3](#) &pnt)
- std::istream & **operator**>> (std::istream &stream, [Point3](#) &pnt)
- double [sqDistance](#) (const [Point3](#) &p0, const [Point3](#) &p1)  
*Get the squared distance between two points.*
- double [sqDistance](#) (const [Point3](#) \*p0, const [Point3](#) \*p1)  
*Get the squared distance between two points.*
- double [distance](#) (const [Point3](#) &p0, const [Point3](#) &p1)  
*Get the squared distance between two points.*
- [Point3](#) center (const [Point3](#) &p0, const [Point3](#) &p1)  
*Midpoint of p0 and p1.*
- std::ostream & **operator**<< (std::ostream &stream, const [Vector3](#) &vec)
- [Vector3](#) crossProduct (const [Vector3](#) &vec0, const [Vector3](#) &vec1)  
*Cross product.*
- [Vector3](#) normalize (const [Vector3](#) &other)  
*Normalize.*
- [Vector3](#) **operator-** (const [Vector3](#) &in)
- [Vector3](#) **operator\*** (double d, const [Vector3](#) &vec)
- [Vector3](#) **operator+** (const [Vector3](#) &vec0, const [Vector3](#) &vec1)
- [Vector3](#) **operator-** (const [Vector3](#) &vec0, const [Vector3](#) &vec1)
- int [getLicenseState](#) ()  
*Check the license state.*
- void [printLicense](#) ()  
*Print license details.*
- bool [isPure](#) ()  
*Check if pure or lm build.*
- bool [activateWof](#) (const char \*key, bool bSystemWide)  
*Activate WOF license.*
- bool [deactivateWof](#) ()  
*Deactivate WOF license.*
- bool [extendTrial](#) (const char \*key)  
*Extend Trial.*
- void [printVersion](#) ()  
*Print version number.*
- void [getVersion](#) (int &versionMajor, int &versionMinor)  
*Get version numbers.*

- bool [isRelease](#) ()  
*Check if the present binary is a Release or Debug build.*
- [MeshPtr melt](#) (std::vector< [Point3](#) > &vInputCorners, double avgLength, double featureThresh=15.0)  
*Remesh (melt) a triangle mesh.*
- [MeshPtr reconstruct\\_auto](#) (std::vector< [Point3](#) > &vPoints, bool bAllowSmoothing, double sfactor=2.0, int numGrowSteps=10)  
*Reconstruct with an automatic spacing value.*
- [MeshPtr reconstruct\\_abs](#) (std::vector< [Point3](#) > &vPoints, bool bAllowSmoothing, double spacingAbs, int numGrowSteps=10)  
*Reconstruct with an absolute spacing value.*
- void [toCloud](#) (std::vector< [Point3](#) > &vCornersIn, double length, double featureThresh, std::vector< [Point3](#) > &vCloudOut)  
*Mesh-to-Cloud.*
- void [edgeFlips](#) ([MeshPtr](#) pMesh)  
*Flip edges.*
- void [edgeFlipsSimA](#) ([MeshPtr](#) pMesh)  
*Flip edges - simulated annealing.*
- void [laplacianSmoothing](#) ([MeshPtr](#) pMesh, int numIterations)  
*Laplacian smoothing.*
- int [reduce](#) ([MeshPtr](#) pMesh, double targetLen=DBL\_MAX, double maxDev=2.0)  
*Reduce.*
- void [subscribe](#) ([ProgressBase](#) \*pProgressBase)  
*Subscribe to progress updates.*
- [FileType](#) [getFileType](#) (const std::string &filename)  
*Get File Type.*
- bool [writePoints\\_ASCII](#) (const char \*filename, const std::vector< [Point3](#) > &vPoints)  
*Write points to an ASCII file.*
- bool [writePoints\\_BIN](#) (const char \*filename, std::vector< [Point3](#) > &vPoints)  
*Write points to a binary file.*
- bool [readPly](#) (const char \*filename, bool bReadPoints, std::vector< [Point3](#) > &vPointsOut)  
*Write points to a \*.ply file.*
- bool [writePointsPly](#) (const std::string &filename, std::vector< [GEOM\\_WOF::Point3](#) > &vPoints, bool bASCII)
- bool [readPoints\\_ASCII](#) (const char \*filename, std::vector< [Point3](#) > &vPoints)  
*Read points from an ASCII file.*
- bool [readPoints\\_BIN](#) (const char \*filename, std::vector< [Point3](#) > &vPointsOut)  
*Read points from a binary file.*
- bool [readSTL\\_ASCII](#) (const char \*filename, std::vector< [Point3](#) > &vTriangleCorners)  
*Read a mesh from ASCII STL.*
- bool [readPoints\\_auto](#) (std::string &inFilename, std::vector< [Point3](#) > &vPoints)  
*Read points from a file (automatic detection)*
- bool [writePoints\\_auto](#) (std::string &outFilename, std::vector< [Point3](#) > &vPoints, bool bASCII)  
*Write points to a file.*
- bool [writeMesh\\_auto](#) (const std::string &filename, std::shared\_ptr< [Mesh](#) > pMesh, bool bASCII)  
*Write mesh to a file.*

### 8.1.1 Detailed Description

Namespace [GEOM\\_WOF](#)

Namespace of the WOF library

### 8.1.2 Typedef Documentation

### 8.1.2.1 MeshPtr `typedef std::shared_ptr<Mesh> GEOM_WOF::MeshPtr`

MeshPtr is a shared pointer to [Mesh](#)

## 8.1.3 Function Documentation

### 8.1.3.1 subscribe() `void GEOM_WOF::subscribe ( ProgressBase * pProgressBase )`

You can provide your own progress receiver class (e.g. progress bar) deriving from [ProgressBase](#). Whenever the progress state changes its update method [ProgressBase::update\(\)](#) will be called.

## 9 Class Documentation

### 9.1 GEOM\_WOF::Mesh Class Reference

3D [Mesh](#) class  
`#include <Mesh.h>`

#### Public Member Functions

- [Mesh](#) (RMesh \*pRMesh)  
*Constructor.*
- [~Mesh](#) ()  
*Destructor.*
- **Mesh** (const [Mesh](#) &)=delete
- [Mesh](#) & **operator=** (const [Mesh](#) &)=delete
- void [getTriangles](#) (std::vector< [Point3](#) \* > &vTriangleCorners) const  
*Get Triangles.*
- void [getPoints](#) (std::vector< [Point3](#) \* > &vPoints) const  
*Get Points.*
- void [getVertexIndexData](#) (std::vector< [Point3](#) \* > &vVertices, std::vector< int > &vCornerIndices) const  
*Get the [Mesh](#) as Vertices and Indices.*
- bool [writePly\\_BIN](#) (const std::string &name) const  
*Write Ply (Binary)*
- bool [writePly\\_ASCII](#) (const std::string &name) const  
*Write Ply (ASCII)*
- bool [writeGeomview\\_ASCII](#) (const std::string &name) const  
*Write Geomview.*
- bool [writeStl\\_ASCII](#) (const std::string &name) const  
*Write STL (ASCII)*
- void [printStats](#) (const std::string &name) const  
*Print Statistics.*
- double [getAverageEdgeLength](#) () const  
*Get the average edge length.*

#### 9.1.1 Detailed Description

The [Mesh](#) is a 3D triangle mesh.

#### 9.1.2 Member Function Documentation

**9.1.2.1 getAverageEdgeLength()** `double GEOM_WOF::Mesh::getAverageEdgeLength ( ) const`  
 Computes and returns the average edge length

**9.1.2.2 getPoints()** `void GEOM_WOF::Mesh::getPoints (   
 std::vector< Point3 * > & vPoints ) const`

#### Parameters

|     |                |                                       |
|-----|----------------|---------------------------------------|
| out | <i>vPoints</i> | is used to return the vertex pointers |
|-----|----------------|---------------------------------------|

**9.1.2.3 getTriangles()** `void GEOM_WOF::Mesh::getTriangles (   
 std::vector< Point3 * > & vTriangleCorners ) const`

#### Parameters

|     |                         |   |
|-----|-------------------------|---|
| out | <i>vTriangleCorners</i> | is used to return the triangles as 3 vertex pointers per triangle. The order of the corners per triangle is counterclockwise. |
|-----|-------------------------|---|

**9.1.2.4 getVertexIndexData()** `void GEOM_WOF::Mesh::getVertexIndexData (   
 std::vector< Point3 * > & vVertices,   
 std::vector< int > & vCornerIndices ) const`

#### Parameters

|                       |  |
|-----------------------|--|
| <i>vVertices</i>      | [out] The vertices of the <a href="#">Mesh</a>   |
| <i>vCornerIndices</i> | [out] Three subsequent indices for each triangle. The indices refer to points in vVertices and thus the index range starts with 0. |

#### Note

There are file formats (e.g., \*.obj) where the first index must be 1, not 0! Simply increment the indices by 1 then.

**9.1.2.5 printStatistics()** `void GEOM_WOF::Mesh::printStatistics (   
 const std::string & name ) const`

Prints mesh statistics to stdout

#### Parameters

|             |   |
|-------------|---|
| <i>name</i> | serves as arbitrary identifier that is also printed to stdout |
|-------------|---|

**9.1.2.6 writeGeomview\_ASCII()** `bool GEOM_WOF::Mesh::writeGeomview_ASCII (   
 const std::string & name ) const`

Writes a file for the Geomview viewer

#### Parameters

|             |                              |
|-------------|------------------------------|
| <i>name</i> | [in] is the output filename. |
|-------------|------------------------------|

**9.1.2.7 writePly\_ASCII()** `bool GEOM_WOF::Mesh::writePly_ASCII (`  
`const std::string & name ) const`

Writes an ASCII PLY file

**Parameters**

|             |                              |
|-------------|------------------------------|
| <i>name</i> | [in] is the output filename. |
|-------------|------------------------------|

**9.1.2.8 writePly\_BIN()** `bool GEOM_WOF::Mesh::writePly_BIN (`  
`const std::string & name ) const`

Writes a binary PLY file

**Parameters**

|             |                              |
|-------------|------------------------------|
| <i>name</i> | [in] is the output filename. |
|-------------|------------------------------|

**9.1.2.9 writeStl\_ASCII()** `bool GEOM_WOF::Mesh::writeStl_ASCII (`  
`const std::string & name ) const`

Writes an ASCII STL file

**Parameters**

|             |                              |
|-------------|------------------------------|
| <i>name</i> | [in] is the output filename. |
|-------------|------------------------------|

The documentation for this class was generated from the following file:

- Mesh.h

## 9.2 GEOM\_WOF::Point3 Class Reference

3D Point

```
#include <Point3.h>
```

### Public Member Functions

- [Point3](#) (const double x\_, const double y\_, const double z\_)  
*Constructor.*
- [Point3](#) ()  
*Default constructor.*
- [Point3](#) (const [Point3](#) &p\_)  
*Copy constructor.*
- [Point3](#) & [operator=](#) (const [Point3](#) &other)  
*operator=*
- [~Point3](#) ()  
*Destructor.*
- double [x](#) () const  
*Get the x-coordinate.*
- double [y](#) () const  
*Get the y-coordinate.*

- double **z** () const  
*Get the z-coordinate.*
- void **xyz** (double &x\_, double &y\_, double &z\_) const  
*Get the x-, y- and z-coordinate.*
- void **addOwnCoords** (double &x, double &y, double &z) const  
*Add the point's coordinates to x,y,z.*
- void **addWeightedOwnCoords** (double weight, double &x, double &y, double &z) const  
*Add the point's weighted coordinates to x,y,z.*
- bool **operator<** (const **Point3** &p) const  
*Less than operator.*
- bool **operator>** (const **Point3** &p) const  
*Greater than operator.*
- bool **operator==** (const **Point3** &p) const  
*Equality operator.*
- bool **operator!=** (const **Point3** &p) const  
*Inequality operator.*
- void **set** (const double x\_, const double y\_, const double z\_)  
*Set the coordiantes.*
- void **set** (const **Point3** &pnt)  
*Set the coordiantes.*
- **Vector3 operator-** (const **Point3** &other) const  
*operator-*
- **Point3 operator+** (const **Vector3** &vec) const  
*operator+*
- **Point3 operator-** (const **Vector3** &vec) const  
*operator-*

### Protected Attributes

- double **coordX**
- double **coordY**
- double **coordZ**

### Friends

- std::ostream & **operator<<** (std::ostream &stream, const **Point3** &pnt)
- std::istream & **operator>>** (std::istream &stream, **Point3** &pnt)

## 9.2.1 Constructor & Destructor Documentation

**9.2.1.1 Point3()** [1/3] GEOM\_WOF::Point3::Point3 (  
const double x\_,  
const double y\_,  
const double z\_ ) [inline]

### Parameters

|                                  |                  |
|----------------------------------|------------------|
| $x_, y_ \leftrightarrow$<br>$z_$ | [in] coordinates |
|----------------------------------|------------------|

**9.2.1.2 Point3()** [2/3] `GEOM_WOF::Point3::Point3 ( ) [inline]`  
 Coordinates are initialized to 0.

**9.2.1.3 Point3()** [3/3] `GEOM_WOF::Point3::Point3 (`  
`const Point3 & p_ ) [inline]`  
 Copies the coordinates of `p_`

## 9.2.2 Member Function Documentation

**9.2.2.1 addOwnCoords()** `void GEOM_WOF::Point3::addOwnCoords (`  
`double & x,`  
`double & y,`  
`double & z ) const [inline]`

### Parameters

|                    |  |
|--------------------|--|
| <code>x,y,z</code> | [inout] are used to accumulate the point's coordinates |
|--------------------|--|

**9.2.2.2 addWeightedOwnCoords()** `void GEOM_WOF::Point3::addWeightedOwnCoords (`  
`double weight,`  
`double & x,`  
`double & y,`  
`double & z ) const [inline]`

### Parameters

|                     |  |
|---------------------|--|
| <code>weight</code> | is a factor on <code>x,y,z</code>                      |
| <code>x,y,z</code>  | [inout] are used to accumulate the point's coordinates |

**9.2.2.3 operator!=(=)** `bool GEOM_WOF::Point3::operator!= (`  
`const Point3 & p ) const [inline]`

### Parameters

|                |  |
|----------------|--|
| <code>p</code> | [in] The point whose coordinates are compared with the ones of the present point |
|----------------|--|

**9.2.2.4 operator+()** `Point3 GEOM_WOF::Point3::operator+ (`  
`const Vector3 & vec ) const [inline]`

### Returns

a point that corresponds to the present point moved by `vec`

**9.2.2.5 operator-()** [1/2] `Vector3 GEOM_WOF::Point3::operator- (`  
`const Point3 & other ) const [inline]`



## Returns

the difference vector ( *\*this* - *other*) i.e., a vector pointing from the point *other* to *\*this*.

**9.2.2.6 operator-()** [2/2] `Point3 GEOM_WOF::Point3::operator- ( const Vector3 & vec ) const [inline]`

## Returns

a point that corresponds to the present point moved by *vec*

**9.2.2.7 operator<()** `bool GEOM_WOF::Point3::operator< ( const Point3 & p ) const [inline]`

## Parameters

|          |                                    |
|----------|------------------------------------|
| <i>p</i> | [in] is compared with <i>*this</i> |
|----------|------------------------------------|

## Returns

true if the coordinates of the present point are lexicographically smaller than the ones of *p* or false otherwise

**9.2.2.8 operator=()** `Point3& GEOM_WOF::Point3::operator= ( const Point3 & other ) [inline]`

Assigns *other*

**9.2.2.9 operator==()** `bool GEOM_WOF::Point3::operator== ( const Point3 & p ) const [inline]`

## Parameters

|          |  |
|----------|--|
| <i>p</i> | [in] The point whose coordinates are compared with the ones of the present point |
|----------|--|

**9.2.2.10 operator>()** `bool GEOM_WOF::Point3::operator> ( const Point3 & p ) const [inline]`

## Parameters

|          |  |
|----------|--|
| <i>p</i> | [in] The point whose coordinates are compared with the ones of the present point |
|----------|--|

## Returns

true if the coordinates of the present point are lexicographically greater than the ones of *p* or false otherwise

**9.2.2.11 set()** [1/2] `void GEOM_WOF::Point3::set ( const double x_, const double y_, const double z_ ) [inline]`

Set the coordinates of the present point to *x\_*,*y\_*,*z\_*.

**Parameters**

|                              |   |
|------------------------------|---|
| $x_, y_, z_ \leftrightarrow$ | [in] are the coordinates to be assigned |
|------------------------------|---|

**9.2.2.12 set()** [2/2] `void GEOM_WOF::Point3::set ( const Point3 & pnt ) [inline]`

Set the coordinates of the present point to the ones of pnt

**Parameters**

|            |  |
|------------|--|
| <i>pnt</i> | carries the coordinates to be assigned |
|------------|--|

**9.2.2.13 x()** `double GEOM_WOF::Point3::x ( ) const [inline]`

**Returns**

the x-coordinate

**9.2.2.14 xyz()** `void GEOM_WOF::Point3::xyz ( double & x_, double & y_, double & z_ ) const [inline]`

**Parameters**

|                              |                         |
|------------------------------|-------------------------|
| $x_, y_, z_ \leftrightarrow$ | [out] x,y,z-coordinates |
|------------------------------|-------------------------|

**Returns**

all 3 coordinates at once

**9.2.2.15 y()** `double GEOM_WOF::Point3::y ( ) const [inline]`

**Returns**

the y-coordinate

**9.2.2.16 z()** `double GEOM_WOF::Point3::z ( ) const [inline]`

**Returns**

the z-coordinate

The documentation for this class was generated from the following file:

- [Point3.h](#)

## 9.3 GEOM\_WOF::ProgressBase Class Reference

Base class for progress subscribers.

```
#include <wof_api_definitions.h>
```

### Public Member Functions

- virtual void [update](#) (const std::string &s, double d)=0  
*update*

#### 9.3.1 Detailed Description

A progress subscriber class can be derived from [ProgressBase](#) to receive progress updates from the WOF library. A simple terminal progress bar could be derived like this:

```
class MyProgressBar:public GEOM_WOF::ProgressBase
{
public:
    // WOF calls the update method with d={0.0,...,1.0}
    void update(const std::string& s,double d)
    {
        if(s!=lastMessage)
        {
            cout<<"\n"; // New message, line feed
            lastMessage=s;
        }
        cout<<("Progress(\""+s+"\" ): ")<<d*100.0<<" %
        if(d>=1.0) cout<<endl;
    }
protected:
    std::string lastMessage;
};
```

#### 9.3.2 Member Function Documentation

**9.3.2.1 update()** virtual void GEOM\_WOF::ProgressBase::update (   
const std::string & s,   
double d ) [pure virtual]

This method must be defined in the derived class. It is called whenever the progress changes and thus it should be computationally inexpensive.

The documentation for this class was generated from the following file:

- [wof\\_api\\_definitions.h](#)

## 9.4 GEOM\_WOF::TimerC Class Reference

Timer class.

```
#include <TimerC.h>
```

### Public Member Functions

- [TimerC](#) ()  
*Constructor.*
- double [stop](#) ()  
*Timer stop.*
- double [get](#) () const  
*Get the elapsed time.*
- void [report](#) (const std::string &s)  
*Report.*

#### 9.4.1 Detailed Description

[TimerC](#) measures the time consumption

## 9.4.2 Constructor & Destructor Documentation

### 9.4.2.1 `TimerC()` `GEOM_WOF::TimerC::TimerC ( ) [inline]`

At construction `TimerC` stores the current time

## 9.4.3 Member Function Documentation

### 9.4.3.1 `get()` `double GEOM_WOF::TimerC::get ( ) const [inline]`

#### Returns

the elapsed time in seconds between `TimerC` construction and the first call to `TimerC::stop()`. When the timer has not been stopped then the time since construction is returned.

### 9.4.3.2 `report()` `void GEOM_WOF::TimerC::report ( const std::string & s ) [inline]`

Prints the time since construction or since last report. This command is intended to measure successive intervals

### 9.4.3.3 `stop()` `double GEOM_WOF::TimerC::stop ( ) [inline]`

#### Returns

the elapsed time since `TimerC` construction in seconds

The documentation for this class was generated from the following file:

- `TimerC.h`

## 9.5 `GEOM_WOF::Vector3` Class Reference

3D Vector

```
#include <Vector3.h>
```

### Public Member Functions

- `Vector3` (const double x\_, const double y\_, const double z\_)  
*Constructor.*
- `Vector3` ()  
*Default constructor.*
- `Vector3` (const `Vector3` &v\_)  
*Copy constructor.*
- bool `isDegenerate` () const  
*isDegenerate*
- void `xyz` (double &x\_, double &y\_, double &z\_) const  
*Get x,y,z.*
- double `x` () const  
*Get the x-value.*
- double `y` () const  
*Get the y-value.*
- double `z` () const  
*Get the z-value.*
- void `set` (const double x\_, const double y\_, const double z\_)

- Set  $x, y, z$ .
- void **add** (const [Vector3](#) &other)  
Add a [Vector3](#) to the present one.
- void **sub** (const [Vector3](#) &other)
- void **div** (double div)
- void **mul** (double mul)
- double **sqlength** () const  
Get the squared length of the vector.
- int **getMaxAbsIndex** () const  
Get max index.
- double **getMaxComponent** () const  
Get max component.
- double **getMaxAbsComponent** () const  
Get max absolute component.
- double **getCartesian** (int i) const  
Get component  $i$ .
- double **length** () const  
Get the length of the vector.
- double **operator\*** (const [Vector3](#) &other) const  
Scalar product.
- [Vector3](#) **operator\*** (double val) const  
Multiply by a scalar value.
- [Vector3](#) **operator/** (double val) const  
Divide by a scalar value.
- [Vector3](#) & **operator=** (const [Vector3](#) &other)  
Equality operator.
- [Vector3](#) & **operator+=** (const [Vector3](#) &other)
- [Vector3](#) & **operator-=** (const [Vector3](#) &other)
- [Vector3](#) & **operator/=** (double div)
- [Vector3](#) & **operator\*=** (double mul)

### Protected Attributes

- double **valX**
- double **valY**
- double **valZ**

### 9.5.1 Constructor & Destructor Documentation

**9.5.1.1 Vector3()** [1/3] `GEOM_WOF::Vector3::Vector3 (`  
`const double x_,`  
`const double y_,`  
`const double z_ )`

#### Parameters

|              |                                 |
|--------------|---------------------------------|
| $x_, y_, z_$ | Values to initialize the Vector |
|--------------|---------------------------------|

**9.5.1.2 Vector3()** [2/3] `GEOM_WOF::Vector3::Vector3 ( )`

The vector is initialized to (0,0,0)

**9.5.1.3 Vector3()** [3/3] `GEOM_WOF::Vector3::Vector3 (`  
`const Vector3 & v_ )`

Copies `v_`

## 9.5.2 Member Function Documentation

**9.5.2.1 add()** `void GEOM_WOF::Vector3::add (`  
`const Vector3 & other ) [inline]`

Parameters

|              |   |
|--------------|---|
| <i>other</i> | is added to the present <a href="#">Vector3</a> |
|--------------|---|

**9.5.2.2 getCartesian()** `double GEOM_WOF::Vector3::getCartesian (`  
`int i ) const`

Returns

the *i*-th component

**9.5.2.3 getMaxAbsComponent()** `double GEOM_WOF::Vector3::getMaxAbsComponent ( ) const`

Returns

the maximum absolute component

**9.5.2.4 getMaxAbsIndex()** `int GEOM_WOF::Vector3::getMaxAbsIndex ( ) const`

Returns

the index of the largest absolute component (0,1 or 2)

**9.5.2.5 getMaxComponent()** `double GEOM_WOF::Vector3::getMaxComponent ( ) const [inline]`

Returns

the maximum component

**9.5.2.6 isDegenerate()** `bool GEOM_WOF::Vector3::isDegenerate ( ) const`

Returns

true if the vector length is 0, false otherwise.

**9.5.2.7 length()** `double GEOM_WOF::Vector3::length ( ) const`

Returns

the length of the vector

**9.5.2.8 operator\*()** [1/2] `double GEOM_WOF::Vector3::operator* ( const Vector3 & other ) const`

Returns

the scalar product of the present [Vector3](#) and `other`

**9.5.2.9 operator\*()** [2/2] `Vector3 GEOM_WOF::Vector3::operator* ( double val ) const`

Returns

the present [Vector3](#) multiplied by `val`

**9.5.2.10 operator/()** `Vector3 GEOM_WOF::Vector3::operator/ ( double val ) const`

Returns

the present [Vector3](#) divided by `val`

**9.5.2.11 operator=()** `Vector3& GEOM_WOF::Vector3::operator= ( const Vector3 & other )`

Returns

true when the present [Vector3](#) has the same x,y,z-values as `other`

**9.5.2.12 set()** `void GEOM_WOF::Vector3::set ( const double x_, const double y_, const double z_ )`

Assigns values to the present [Vector3](#)

Parameters

|                                  |                  |
|----------------------------------|------------------|
| $x_, y_ \leftrightarrow$<br>$z_$ | Values to assign |
|----------------------------------|------------------|

**9.5.2.13 sqLength()** `double GEOM_WOF::Vector3::sqLength ( ) const`

Returns

the squared length of the [Vector3](#)

**9.5.2.14 x()** `double GEOM_WOF::Vector3::x ( ) const [inline]`

Returns

x

**9.5.2.15 xyz()** `void GEOM_WOF::Vector3::xyz (`  
    `double & x_,`  
    `double & y_,`  
    `double & z_ ) const [inline]`

Parameters

|                       |   |
|-----------------------|---|
| <code>x_,y_,z_</code> | [out] Used to return the x,y,z-values of the Vector |
|-----------------------|---|

**9.5.2.16 y()** `double GEOM_WOF::Vector3::y ( ) const [inline]`

Returns

y

**9.5.2.17 z()** `double GEOM_WOF::Vector3::z ( ) const [inline]`

Returns

z

The documentation for this class was generated from the following file:

- Vector3.h

## 9.6 GEOM\_WOF::WofBugException Struct Reference

Bug-Exception.

`#include <wof_api_definitions.h>`

Inherits `std::exception`.

### Public Member Functions

- virtual const char \* **what** () const throw ()

#### 9.6.1 Detailed Description

The [WofBugException](#) is thrown in case of unexpected states caused by invalid input **OR** a bug. Software quality is very important for this project. If you find a bug, send a bug report and it will be processed immediately.

The documentation for this struct was generated from the following file:

- [wof\\_api\\_definitions.h](#)

## 9.7 GEOM\_WOF::WofLicenseException Class Reference

License-Exception.

`#include <wof_api_definitions.h>`

Inherits `std::exception`.



### 9.7.1 Detailed Description

The [WofLicenseException](#) is thrown in case of an invalid license state. If your trial has expired but you still need the software for your non-commercial research, contact Geom Software: [bkorn@geom.at](mailto:bkorn@geom.at) for a trial extension code. Include information about your project.

The documentation for this class was generated from the following file:

- [wof\\_api\\_definitions.h](#)

## 10 File Documentation

### 10.1 wof\_api.h File Reference

```
#include <vector>
#include "License.h"
#include "wof_api_io.h"
#include "wof_api_functions.h"
#include "wof_api_definitions.h"
#include "TimerC.h"
```

#### Namespace

- [GEOM\\_WOF](#)

#### Macros

- `#define` [WOFLIC\\_ACTIVATED](#) 10
- `#define` [WOFLIC\\_GRACE\\_OK](#) 11
- `#define` [WOFLIC\\_GRACE\\_EXPIRED](#) 12
- `#define` [WOFLIC\\_TRIAL](#) 13
- `#define` [WOFLIC\\_INVALID](#) 14
- `#define` [WOFLIC\\_PURE](#) 15

#### Functions

- `int` [GEOM\\_WOF::getLicenseState](#) ()  
*Check the license state.*
- `void` [GEOM\\_WOF::printLicense](#) ()  
*Print license details.*
- `bool` [GEOM\\_WOF::isPure](#) ()  
*Check if pure or lm build.*
- `bool` [GEOM\\_WOF::activateWof](#) (const char \*key, bool bSystemWide)  
*Activate WOF license.*
- `bool` [GEOM\\_WOF::deactivateWof](#) ()  
*Deactivate WOF license.*
- `bool` [GEOM\\_WOF::extendTrial](#) (const char \*key)  
*Extend Trial.*
- `void` [GEOM\\_WOF::printVersion](#) ()  
*Print version number.*
- `void` [GEOM\\_WOF::getVersion](#) (int &versionMajor, int &versionMinor)  
*Get version numbers.*
- `bool` [GEOM\\_WOF::isRelease](#) ()  
*Check if the present binary is a Release or Debug build.*

## 10.2 wof\_api\_definitions.h File Reference

### Classes

- class [GEOM\\_WOF::WofLicenseException](#)  
*License-Exception.*
- struct [GEOM\\_WOF::WofBugException](#)  
*Bug-Exception.*
- class [GEOM\\_WOF::ProgressBase](#)  
*Base class for progress subscribers.*

### Namespace

- [GEOM\\_WOF](#)

### Macros

- `#define WOF_VER_MAJOR 1`
- `#define WOF_VER_MINOR 12`
- `#define CLASS_DECLSPEC`

## 10.3 wof\_api\_functions.h File Reference

```
#include <vector>
#include <float.h>
#include "Point3.h"
#include "Mesh.h"
```

### Namespace

- [GEOM\\_WOF](#)

### Functions

- MeshPtr [GEOM\\_WOF::melt](#) (std::vector< Point3 > &vInputCorners, double avgLength, double featureThresh=15.0)  
*Remesh (melt) a triangle mesh.*
- MeshPtr [GEOM\\_WOF::reconstruct\\_auto](#) (std::vector< Point3 > &vPoints, bool bAllowSmoothing, double sfactor=2.0, int numGrowSteps=10)  
*Reconstruct with an automatic spacing value.*
- MeshPtr [GEOM\\_WOF::reconstruct\\_abs](#) (std::vector< Point3 > &vPoints, bool bAllowSmoothing, double spacingAbs, int numGrowSteps=10)  
*Reconstruct with an absolute spacing value.*
- void [GEOM\\_WOF::toCloud](#) (std::vector< Point3 > &vCornersIn, double length, double featureThresh, std::vector< Point3 > &vCloudOut)  
*Mesh-to-Cloud.*
- void [GEOM\\_WOF::edgeFlips](#) (MeshPtr pMesh)  
*Flip edges.*
- void [GEOM\\_WOF::edgeFlipsSimA](#) (MeshPtr pMesh)  
*Flip edges - simulated annealing.*
- void [GEOM\\_WOF::laplacianSmoothing](#) (MeshPtr pMesh, int numIterations)  
*Laplacian smoothing.*
- int [GEOM\\_WOF::reduce](#) (MeshPtr pMesh, double targetLen=DBL\_MAX, double maxDev=2.0)  
*Reduce.*
- void [GEOM\\_WOF::subscribe](#) (ProgressBase \*pProgressBase)  
*Subscribe to progress updates.*

## 10.4 wof\_api\_io.h File Reference

```
#include <vector>
#include "Point3.h"
#include "Mesh.h"
```

### Namespace

- [GEOM\\_WOF](#)

### Enumerations

- enum [GEOM\\_WOF::FileType](#) {  
[GEOM\\_WOF::FT\\_STL](#) , [GEOM\\_WOF::FT\\_PLY](#) , [GEOM\\_WOF::FT\\_XYZ](#) , [GEOM\\_WOF::FT\\_BIN](#) ,  
[GEOM\\_WOF::FT\\_LIST](#) , [GEOM\\_WOF::FT\\_UNKNOWN](#) }

*Filetype.*

### Functions

- FileType [GEOM\\_WOF::getFileType](#) (const std::string &filename)  
*Get File Type.*
- bool [GEOM\\_WOF::writePoints\\_ASCII](#) (const char \*filename, const std::vector< Point3 > &vPoints)  
*Write points to an ASCII file.*
- bool [GEOM\\_WOF::writePoints\\_BIN](#) (const char \*filename, std::vector< Point3 > &vPoints)  
*Write points to a binary file.*
- bool [GEOM\\_WOF::readPly](#) (const char \*filename, bool bReadPoints, std::vector< Point3 > &vPointsOut)  
*Write points to a \*.ply file.*
- bool [GEOM\\_WOF::writePointsPly](#) (const std::string &filename, std::vector< [GEOM\\_WOF::Point3](#) > &vPoints, bool bASCII)
- bool [GEOM\\_WOF::readPoints\\_ASCII](#) (const char \*filename, std::vector< Point3 > &vPoints)  
*Read points from an ASCII file.*
- bool [GEOM\\_WOF::readPoints\\_BIN](#) (const char \*filename, std::vector< Point3 > &vPointsOut)  
*Read points from a binary file.*
- bool [GEOM\\_WOF::readSTL\\_ASCII](#) (const char \*filename, std::vector< Point3 > &vTriangleCorners)  
*Read a mesh from ASCII STL.*
- bool [GEOM\\_WOF::readPoints\\_auto](#) (std::string &inFilename, std::vector< Point3 > &vPoints)  
*Read points from a file (automatic detection)*
- bool [GEOM\\_WOF::writePoints\\_auto](#) (std::string &outFilename, std::vector< Point3 > &vPoints, bool bASCII)  
*Write points to a file.*
- bool [GEOM\\_WOF::writeMesh\\_auto](#) (const std::string &filename, std::shared\_ptr< Mesh > pMesh, bool bASCII)  
*Write mesh to a file.*



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